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Abstract:

The core focus of WP5 is the generalization of the action representation developed in WP2, WP3, and WP4 to cover communicative acts, and the formalization of syntax and semantics for communication and interaction in natural language with situated purposeful agents, together with mechanisms for the acquisition of grammar from sentence-meaning pairs. The deliverable and the attached paper are exclusively concerned with the nature of the problem of language acquisition on the basis of paired presentations of sentences of any human language and contextually supported meanings for those sentences. The paper shows that a very simple statistical model can simulate the general course of acquisition, including certain patterns of overgeneralization, without adherence to any subset principle, and without the use of parametric triggers and attendant ordering principles that have been postulated in the recent literature.

Keyword list: Combinatory Categorical Grammar (CCG); Language Acquisition; Grammatical Bootstrapping; Generative Statistical Models of Grammars and Parsers

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1. Executive Summary

The core focus of WP5 is the generalization of the action representation developed in WP2, WP3 and WP4 to cover communicative acts, and the formalization of syntax and semantics for communication and interaction in natural language with situated purposeful agents, together with mechanisms for the acquisition of grammar from sentence-meaning pairs. The deliverable and the attached paper are exclusively concerned with the nature of the problem of language acquisition on the basis of paired presentations of sentences of any human language and contextually supported meanings for those sentences. The paper shows that a very simple statistical model can simulate the general course of acquisition, including certain patterns of overgeneralization, without adherence to any subset principle, and without the use of parametric triggers and attendant ordering principles that have been postulated in the recent literature. The associated deliverable D5.1 shows how the LDEC action representation and the associated PKS planner developed under WP4 and described in D4.3.1 can both be induced from lower-level representations of states and state transitions, and provide a basis for natural language semantics at the higher level of Combinatory Categorical Grammar, providing the input to the system for either the child or the PACOPLUS agent. Both of these papers are theoretical and look ahead to the next phase of the project, as was anticipated in the plan of work in the annex, and the account of KRA 4 in the Annex (Section 6), since at this stage the low-level modules are not delivering object-concepts at a level appropriate to the formulation of semantics. In particular linguistic semantics grounded in robot sensory-motor schemata that will provide the basis for learning is yet to be developed.

Combinatory Categorical Grammar (CCG, Steedman 2000) is a theory of grammar according to which all language-specific grammatical information resides in the lexicon. A small universal set of strictly type-driven, non-structure dependent, syntactic rules (based on Curry's combinators **B**, **S**, and **T**) then "projects" lexical items into sentence-meaning pairs and defines the mapping from one to the other.

Steedman (2002b,a) showed how the same set of combinatory operations were involved in human and animal non-linguistic planning, and defined a Linear Dynamic version of the Event Calculus (LDEC) as a notation for such a planner. Work by UEDIN under PACOPLUS support reported under deliverable D4.3.1, implements LDEC as a high-level symbolic planner under the PKS framework of Petrick and Bacchus (2002, 2004).

The present report analyzes the problem of connecting this planner to a mechanism for inducing a language-specific CCG grammar from presentations of sentences and (probably ambiguous, possibly noisy) contextually-supported meanings. CCG is being used as a basis for interaction with semantically grounded robots in a number of other European and American projects, notably under EU FP6 IST IP CoSy (Kruijff and Brenner 2006) and in Leslie Kaelbling's group at MIT (Zettlemoyer, Pasula and Kaelbling 2005). The present paper offers a basis for a completely general and strikingly simple account of language acquisition in human and artificial systems for any semantics, including semantics defined on the basis of the kind of dialog actions considered in deliverable D5.1., Annex B. It is potentially applicable to all of these systems.

The document consists of a single paper describing this work, included in the present paper as Annex A.

- A: The Computational Problem of Language Acquisition (to be submitted: presented at the Institute of Research in Cognitive Science (IRCS) Colloquium, University of Pennsylvania, January 2007). This paper outlines a complete model of language acquisition. It uses the framework of CCG but is applicable to any lexicalized grammar formalism, such as Tree adjoining Grammar (TAG, Joshi and Schabes 1992), Lexical-Functional Grammar (LFG, Bresnan 1982), Head driven Phrase-Structure Grammar (HPSG, Pollard and Sag 1994), and Type-Logical Grammar (TLG, Morrill (1994)). To the extent that Construction Grammar (ConstG, Goldberg (1995)) can be lexicalized (which appears to be completely) it also applies to that.

The paper is an extension of work by Zettlemoyer and Collins 2005, who also use CCG as a frame-

work. The present paper differs in doing language learning in the full space of universal grammar as captured in CCG, and in using a generative statistical model, rather than the discriminative Maximum Entropy model used by them. The advantage of a generative model of lexical acquisition is that, because it learns probabilities $P(\text{Syntax}, \text{Semantics} | \text{Word})$ of adult utterance, rather than discriminative weights, the model can be inverted to yield predictions about the probabilities of errorful utterance by the child $P(\text{Word}, \text{Syntax} | \text{Semantics})$. These probabilities can be used to make quantitative predictions about the type of error that will be made by the child under conditions of forced elicitation of the kind investigated by Crain and Thornton (1998), and about the learning curve of the target construction.

2. Role of Language Acquisition in PACOPLUS

The relation of prelinguistic semantics, grounded in sensory motor experience, to high level cognition including language is a central concern of PACOPLUS. The solution presented here to the problem of language acquisition is a very general one. The research has as much to gain from involvement with grounded agents learning action representations as the agents have in terms of provision of spoken interfaces. That is why we are not limiting the language interface to a fixed set of slot-and-filler sentence templates, hand tailored to the PACOPLUS domain, an exercise that would be entirely without scientific interest.

3. Relation to Demonstrator 8.1

The capabilities of Demonstrator 8.1 are decidedly sensory-motor. It is likely that the scope for language learning will be limited, though it will be explored as far as possible. The impact of this research is planned according to the PACOPLUS Annex 1 (see section 6 KRA4) for a later phase, at which point a substantial conceptual base of robot object-action complex (OAC) concepts will have been built up to act as a substrate for a grounded linguistic semantics.

4. Principal Scientific Results

The paper in Annex A shows that the simplest possible generative model predicts the general shape of the child's progress from an initial unstable state in which almost any alternative allowed by universal grammar may be elicited, via a process of exponential reinforcement and extinction which may give the appearance of parametric "switch-setting", to stable adherence to a single form. This result resembles the somewhat different statistical model of Yang (2002), but eschews the use of parameters entirely. It provides a good model for language learning in robots, where problems of error in interpreting the situation and (if standard speech-recognition technology is used) in identifying the string correctly demand a probabilistic approach. There are interesting implications of these results for the purely syntactic, parameter-based approaches of Wexler and Fodor, and for the notion of "syntactic bootstrapping" advanced by Gleitman.

5. Future Work

A number of questions remain open at the time of this report and constitute further work.

1. Children show a number of biases which may work to make this process easier. For example, verbs are acquired later than comparably frequent nouns. It is not clear whether this is an intrinsic cognitive
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intellectual development, or whether it is an artefact of the way the data is presented to the child, and is predicted by the model. Answering this question requires closer attention to corpora like CHILDES than we have so far been able to afford.

2. The actual sensory-motor derived semantics that real children bring to bear on this task is almost entirely opaque. One of the objectives of PACOPLUS is to say what such a semantics might look like. The major effort in the remaining period for this work package is to define such a semantics for the robot agents in its own right, in the hope of shedding light on the nature of the child's own, via exploration of language learning on the basis of such an artificial semantics grounded in sensory motor interaction with the world.

6. Publications Associated with D5.1

1. M. Steedman and J. Hockenmaier, 2006: "The Computational Problem of Language Acquisition" (to be submitted: presented at the Institute of Research in Cognitive Science (IRCS) Colloquium, University of Pennsylvania, January 2007)

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7. Annexes

A. The Computational Problem of Language Acquisition

Mark Steedman and Julia Hockenmaier

CCG is a theory of grammar in which all language-specific grammatical information resides in the lexicon. A small universal set of strictly type-driven, non-structure dependent, syntactic rules (based on Curry’s combinators B, S, and T) then “projects” lexical items into sentence-meaning pairs. The task that faces the child in the earliest stages of language acquisition can therefore be seen as learning a lexicon on the basis of exposure to (probably ambiguous, possibly somewhat noisy) sentence-meaning pairs, given this universal combinatory “projection principle”, and a mapping from semantic types to the set of all universally available lexical syntactic types.

The paper argues that a very simple statistical model allows children to arrive at a target lexicon without navigation of subset principles, or attention to any attendant notion of trigger other than the notion “reasonably short sentence in a reasonably understandable situation drawn from a reasonably representative sample”. The model explains the pattern of errors that have been found in elicitation experiments. The linguistic notion of “parameter” appears to be redundant to this process.

The Computational Problem of Natural Language Acquisition

Annex A

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Abstract

CCG is a theory of grammar in which all language-specific grammatical information resides in the lexicon. A small universal set of strictly type-driven, non-structure dependent, syntactic rules (based on Curry's combinators B, S, and T) then "projects" lexical items into sentence-meaning pairs. The task that faces the child in the earliest stages of language acquisition can therefore be seen as learning a lexicon on the basis of exposure to (probably ambiguous, possibly somewhat noisy) sentence-meaning pairs, given this universal combinatory "projection principle", and a mapping from semantic types to the set of all universally available lexical syntactic types.

The paper argues that a very simple statistical model allows children to arrive at a target lexicon without navigation of subset principles, or attention to any attendant notion of trigger other than the notion "reasonably short sentence in a reasonably understandable situation drawn from a reasonably representative sample". The model explains the pattern of errors that have been found in elicitation experiments. The linguistic notion of "parameter" appears to be redundant to this process.

1 Introduction

It seems highly likely that the child's acquisition of a first language is, in machine learning terms, an ex-

ample of *supervised* learning. That is not to say that they are explicitly instructed by adults, but in coming to know which words of the language are the verbs and which the nouns, and in what linear spatio-temporal order(s) the two may occur, children must have access to something more than the mere strings of words constituting a subset of the legal sentences of the languages.

This agreement is based in part on observation of the extreme rapidity with which language acquisition proceeds, and the absence of negative data. While it is theoretically possible, using probabilistic models and unsupervised machine learning, to approximate grammars of any class to any desired degree of accuracy, the computational costs of such learning for realistic grammars are prohibitive. The consensus also rests on the observation that no-one has actually managed to make these techniques work very well computationally for natural language.

The "something more" that the child brings to language acquisition is sometimes referred to as "Universal Grammar", and as such is sometimes talked about in exclusively syntactic terms, as in the "parameter-setting" account of acquisition of Hyams (1986) and much subsequent work, according to which a homunculus "flips switches" corresponding to syntactic parameters such as head-finality and *pro*-drop until the "universal grammar engine" uniquely specifies the language *modulo* its lexicon, in a process that has been likened to a game of Twenty-Questions (Yang 2006:Ch.7).

Such accounts seem to raise as many questions as they answer about the mechanism by which such learning could proceed. In particular, the specific

inventory of parameters that this universal machine embodies, the way in which the very large search spaces engendered by even quite small sets of binary independent parameter can be effectively explored (Clark & Roberts 1993), and the aspects of the data that “trigger” their setting (Gibson & Wexler 1995) remain rather unclear. One is uneasily reminded of the warnings of Newell (1973) in a different context, concerning the likely outcome of playing Twenty-Questions with nature.

Nevertheless, there is something deeply right in the idea that the process of language learning proceeds by entertaining all possible grammars, and eliminating all alternatives but one, because that is exactly what the child’s developmental behavior looks like, once you know how to look at it. In particular, Crain & Thornton (1998) and their students have shown (using ingeniously forced elicitations) that learning is characterized by great initial variation in productions for any given construction, apparently covering alternatives characteristic of many other languages, followed by abrupt transitions to stable adherence to the correct form for the target language. Yang (2002) offers a probabilistic account of this process in terms of classical Mathematical Learning Theory. While Thornton & Tesan (2006) argue that changes they observe are too abrupt and switch-like to support that particular model, probabilistic models in general are capable of approximating catastrophic, switch-like behavior, so they should not be ruled out.

The present paper uses a computational model derived from work by Siskind (1996), Villavicencio (2002), and Zettlemoyer & Collins (2005) to argue that the notion of parameter setting is meta-theoretical, and entirely redundant to the specification of language learning of this kind. The only notion of trigger that it requires is the notion “reasonably short sentence with an independently accessible meaning”. The only notion of language specific grammar it needs is the lexicon for the language. The only notion of universal grammar that it needs is a universal mapping from each semantic type to the possible lexical types, together with a universal machine for merging or projecting lexical types and their meaning representations onto grammatical derivations.

2 Semantically Grounded Grammar Acquisition

The only remotely plausible source that has ever been proposed for universal grammar is a universal *semantics*, in the form of structured meanings or logical forms to which the child already has access as language acquisition begins, to which syntactic forms are rather directly attached, and which drastically limit the search space.

To say this much is not very helpful in psychological or linguistic terms, since (as Chomsky never tires of pointing out) linguists don’t know that much about how to articulate the semantics. However, the child doesn’t *need* to articulate it. They just need to label it, so our theories need to represent it somehow. As a temporary stopgap we’ll use terms of the lambda calculus, and defer the problem of what the semantics actually looks like till section 5.

This approach makes the child’s problem resemble that of treebank grammar induction for wide coverage parsing (Collins 1997; Charniak 2000; Hockenmaier & Steedman 2002), where sentences hand-annotated with syntactic trees are used to derive a grammar and a statistical parser-model. However, the child’s task is a little harder. First, they have to induce the grammar from strings paired with *unordered logical forms*, rather than language-specific ordered derivation trees. That is, they have to work out *which word(s) go with which element(s) of logical form*, as well as the directionality of the syntactic categories (which are otherwise universally determined by the semantic types of the latter). Second, while they do not seem to have to deal with a greater amount of error than is found in the Penn WSJ treebank (McWhinnie 2005), they may need to deal with *situations which support a number of logical forms*. Third, they need to be able to recover from temporary *wrong lexical assignments*. Fourth, they need to tolerate *lexical ambiguity*.

3 Previous Work

Siskind (1995, 1996), Villavicencio (2002), and Zettlemoyer & Collins (2005) offer computational models of this process, the latter two explicitly using CCG.

Siskind and Villavicencio make strong assumptions about the association of words with elements

of logical form. Both make similarly strong assumptions about universally available parametrically specified rule- or category- types, the latter assuming a type hierarchy. Both deal with noise and homonymy probabilistically.

Both do the learning in two stages, first associating logical forms with words, then inducing phrase structure rules (Siskind) or directional CCG categories (Villavicencio).

However, there is no necessity to separate the two processes of associating meaning and syntactic type. Zettlemoyer and Collins (UAI 2005) combine the two in a single pass CCG induction algorithm. Crucially, their algorithm allows *any contiguous substring* of the sentence to be a lexical item, so that for the given logical form, the learner has to search the cross-product of the substring powerset of the string with the set of pairs of legal categories with substructure powerset of the logical form, as in the example (9) below, for categories that yield combinatory derivations that yield the correct logical form. Learning is via a log-linear model using lexical entries as features and gradient descent on their weights, iterating over successive sentences of a corpus of sentence-logical form pairs.

The algorithm as presented in 2005 learns only a very small rather unambiguous fragment of English, hand-labeled with uniquely identified database queries as logical forms, and an English specific inventory of possible syntactic category types in lieu of Universal Grammar. However, Siskind’s and Villavicencio’s results already tell us that the algorithm should work with multiple candidate logical forms. Similarly, their results show that a universal set of category types can be used without overwhelming the learner.

All of these models depend on availability to the learner of short sentences paired with logical forms, since complexity is determined by a cross-product of powersets both of which are exponential in sentence length. A number of techniques are available to make search efficient including association of incrementally adjusted Bayesian priors with category-types.

Because it allows multiword elements (MWE) to be lexical entries, Zettlemoyer and Collins’ program avoids the problem that two words which consistently collocate, like *want* and *to* fail to reveal which

of them means *want'* and which means *to'*. They can be learned as a single item *want to*. So can idioms and multi-word expressions like “buy the farm,” and “take advantage of”

As with Siskind’s version, lexical items can have complex meanings—corresponding for example to causatives, whose availability may differ (*swim across* vs. *traverser à la nâge*) across languages. No notion of trigger distinct from that of “reasonably simple string-meaning pair” is necessary.

It is possible to use the statistics of the lexicon itself to implicitly represent “parameters” such as verb-finality, via incrementally adjusted prior probabilities on the members of the set of universally available category types.

4 The Proposal

We will assume as a theory of grammar a version of Combinatory Categorical Grammar (CCG, Steedman 2000b; Steedman & Baldridge 2006) in which all language-specific information resides in the lexicon, and a universal set of combinatory rules including functional composition and lexicalized type-raising as well as function application, projects strings of lexical items onto meanings, and vice versa.

The task that faces the child is to learn the categorial lexicon on the basis of exposure to (probably ambiguous, possibly somewhat noisy) sentence-meaning pairs, given this universal combinatory projection principle, and a mapping from semantic types to the set of all universally available lexical syntactic types.

For a corpus of sentences S_i , each with a number of interpretations I_j , each of which has a number of derivations D_k , the relative frequency f of a lexical entry ϕ, σ, μ for a word with phonology ϕ , syntactic category σ and meaning μ is given by:

$$(1) \quad f(\langle \phi, \sigma, \mu \rangle) = \sum_i \sum_j P(I_j | S_i) \sum_k P(D_k | I_j, S_i) \cdot n_{D_k}(\langle \phi, \sigma, \mu \rangle)$$

By Bayes’ Rule,

$$(2) \quad P(D|I, S) = \frac{P(D, I, S)}{P(I, S)} \\ \propto P(D, I, S)$$

We will assume that $P(D, I, S)$ is a generative model for an (exhaustive) parser, rather than the discriminative model of Zettlemoyer & Collins. One

advantage of generative models besides their closeness to competence grammar is that we can invert the parser model to define the probability of an utterance given a meaning.

As the acquisition process begins, this generative model corresponds to the P_{UG} , the probability model of Universal Grammar, which we will assume for present purposes assigns uniform probabilities to everything. This model can be regarded as a log-linear model in which all weights λ_j are unknown and all counts f_j are zero. As the child is exposed to more language, it updates the counts in a language specific model P_G and adjusts a weight λ ($0 \leq \lambda \leq 1$) representing their confidence in G :

$$(3) \quad \tilde{P}(D, I, S) = \lambda \hat{P}_G(D, I, S) + (1 - \lambda) \cdot P_{UG}(D, I, S)$$

The probability of a lexical entry can be defined in terms of (1) as:

$$(4) \quad P_{lex}(\langle \phi, \sigma, \mu \rangle) = \frac{f(\langle \phi, \sigma, \mu \rangle)}{\sum_i f(\langle \phi, \sigma, \mu \rangle_i)}$$

The probability of a semantic interpretation μ_τ of type τ and a syntactic category σ given a word ϕ is given by

$$(5) \quad P(\sigma, \mu_\tau | \phi) = P(\mu_\tau | \phi) \cdot P(\sigma | \mu_\tau, \phi) \approx P(\mu_\tau | \phi) \cdot P(\sigma | \tau)$$

where

$$(6) \quad P(\mu_\tau | \phi) = \sum_i P_{lex}(\langle \phi, \sigma_i, \mu \rangle)$$

and

$$(7) \quad \begin{aligned} P(\sigma | \tau) &= \frac{P(\sigma, \tau)}{P(\tau)} \\ &= \frac{P(\sigma, \tau)}{\sum_i P(\mu_{\tau_i})} \\ &= \frac{P(\sigma, \tau)}{\sum_i \sum_j P_{lex}(\langle \phi_j, \sigma_j, \mu_{\tau_i} \rangle)} \\ &= \frac{\sum_{i,j} P_{lex}(\langle \phi_i, \sigma, \mu_{\tau_j} \rangle)}{\sum_i \sum_j P_{lex}(\langle \phi_j, \sigma_j, \mu_{\tau_i} \rangle)} \end{aligned}$$

Hence, crucially, we can obtain from the above definitions the probability of uttering a word ϕ , such as “more” or “doggies”, given a logical form μ_τ , such as $more'_{((e,t),e)}$, by Bayes’ rule:

$$(8) \quad P(\phi | \mu) = \frac{P(\mu | \phi) \cdot P(\phi_i)}{\sum_i P(\mu | \phi_i) \cdot P(\phi_i)} = \frac{P(\mu | \phi)}{\sum_i P(\mu | \phi_i)}$$

The course of language acquisition can then be accounted for as follows.

4.1 The First Few Words

Consider an adult-accompanied child at Piagetian Stage VI who has yet to learn her first word of such a grammar. She encounters a dog, and shows an interest, but fails to grasp the word “doggie”. Later, she encounters some *more dogs*. The adult observes the child’s evident delight, and says “MORE DOGGIES!”

We can assume that the child has already learned some phonological regularities of the language, and in particular is in a position to consider the possibility that the utterance consists of more than one word (Mattys et al. 1999; Mattys & Juszyk 2001).

What the child must do is consider the cross-product of every non-empty substring ϕ of the utterance “More doggies!” with every connected typed subterm μ_τ of type τ the logical form $more' doggies'$, together with all syntactic categories σ_i that universal grammar allows for the semantic type τ of each such subterm.

We might as a first oversimplification think of the situation as follows:¹

- (9) a. The child thinks: $(more' dogs')_e$
 b. The adult says: “MORE DOGGIES!”
 c. All possible lexical candidates:
- | | |
|----------------|--|
| more:= | NP/N : $more'_{((e,t),e)}$ |
| | $NP \setminus N$: $more'_{((e,t),e)}$ |
| | N : $dogs'_{(e,t)}$ |
| doggies:= | NP/N : $more'_{((e,t),e)}$ |
| | $NP \setminus N$: $more'_{((e,t),e)}$ |
| | N : $dogs'_{(e,t)}$ |
| more doggies:= | NP : $(more' dogs')_e$ |

All of these candidates are permitted by the universal lexical principles of UG. However, not all of them are consistent with this utterance in this language. For some of them, such as $doggies:=NP/N : more'_{((e,t),e)}$, the universal syntactic projection principle of UG fails to offer any derivation yielding $NP : (more' dogs')_e$. Such candidates may be supported by other utterances, but the present utterance does not give any information on them. They are therefore dropped from further consideration in this cycle, leaving the following reduced set of candi-

¹The assumption that the child immediately considers the hypothesis that more is a determiner is particularly far-fetched, and will be reviewed later.

dates:

- (10) The child’s lexical candidates:
 more:= **NP/N : more**_{((e,t),e)}
 $N : dogs'_{(e,t)}$
 doggies:= $NP \setminus N : more'_{((e,t),e)}$
 N : dogs'_(e,t)
 more doggies:= $NP : (more' dogs')_e$

For each of these candidates, if there is not already a corresponding entry in the lexicon, such an entry is added, with a zero count. Then for each candidate, its count is incremented by 1. Since we are assuming this is the first utterance the child has processed, the lexicon now contains two entries for each of the words “more” and “doggies”, each with one count, and one entry for the holophrastic or multiword entity “more doggies”, all with one count. If we assume that the various hypotheses afforded by UG are equiprobable, then by (5) (or by inspection) the conditional probabilities $P(\sigma, \mu | \phi)$ for the former categories are all $\frac{1}{2}$, while that for the latter is 1.

Since for the example so far, $P(\sigma | \mu)$ is always 1, we have the following probabilistic lexicon:

- (11) *The Child’s First Lexicon:*
- | ϕ | σ, μ | f | $P(\sigma, \mu \phi)$ | $P(\phi \mu)$ |
|----------------|---|-----|-------------------------|-----------------|
| more:= | NP/N : more _{((e,t),e)} | 1 | 0.5 | 0.5 |
| | $N : dogs'_{(e,t)}$ | 1 | 0.5 | 0.5 |
| doggies:= | $NP \setminus N : more'_{((e,t),e)}$ | 1 | 0.5 | 0.5 |
| | N : dogs' _(e,t) | 1 | 0.5 | 0.5 |
| more doggies:= | $NP : (more' dogs')_e$ | 1 | 1.0 | 1.0 |

Since the word counts and conditional probabilities for “more” and “doggies” with them meaning $more'_{((e,t),e)}$ are all equal at this stage, the child may well make errors of overgeneration, using some approximation to “doggies” to mean “more”.²

However, even on the basis of this very underspecified lexicon, the child will not overgenerate “*doggies more”. Moreover, further observations involving utterances like “Bad doggies!” “More cookies!”, and “Bad cookies!”, with further updates to frequency counts, will rapidly lower the estimated conditional probability of the spurious hypotheses concerning categories and substrings in comparison to the correct ones, indicated in bold type, as follows:

²The example is constructed, but was inspired by being told of a case in real life when this particular error appears to have occurred (C. Urwin, p.c.).

(12) *The Corpus:*

- a. More doggies!
- b. Bad doggies!
- c. More cookies!
- d. Bad cookies!

$P(\sigma | \mu)$ is still always 1, so the lexicon is now

- (13) *The Child’s Lexicon:*
- | ϕ | σ, μ | f | $P(\sigma, \mu \phi)$ | $P(\phi \mu)$ |
|----------------|---|-----|-------------------------|-----------------|
| more:= | NP/N : more _{((e,t),e)} | 2 | 0.50 | 0.50 |
| | $N : dogs'_{(e,t)}$ | 1 | 0.25 | 0.25 |
| | $N : cookies'_{(e,t)}$ | 1 | 0.25 | 0.25 |
| bad:= | NP/N : bad _{((e,t),e)} | 2 | 0.50 | 0.50 |
| | $N : dogs'_{(e,t)}$ | 1 | 0.25 | 0.25 |
| | $N : cookies'_{(e,t)}$ | 1 | 0.25 | 0.25 |
| doggies:= | $NP \setminus N : more'_{((e,t),e)}$ | 1 | 0.25 | 0.25 |
| | $NP \setminus N : bad'_{((e,t),e)}$ | 1 | 0.25 | 0.25 |
| | N : dogs' _(e,t) | 2 | 0.50 | 0.50 |
| cookies:= | $NP \setminus N : more'_{((e,t),e)}$ | 1 | 0.25 | 0.25 |
| | $NP \setminus N : bad'_{((e,t),e)}$ | 1 | 0.25 | 0.25 |
| | N : cookies' _(e,t) | 2 | 0.50 | 0.25 |
| more doggies:= | $NP : (more' dogs')_e$ | 1 | 1.0 | 1.0 |
| bad doggies:= | $NP : (bad' dogs')_e$ | 1 | 1.0 | 1.0 |
| more cookies:= | $NP : (more' cookies')_e$ | 1 | 1.0 | 1.0 |
| bad cookies:= | $NP : (bad' cookies')_e$ | 1 | 1.0 | 1.0 |

At this point, the child is exponentially less likely to generate “doggie” when she means “more”. By contemplating the definition (8), the reader should be able to satisfy themselves that this effect will be even stronger for more realistic corpora in which the frequency distribution of words is highly skewed, with open class words like “doggie” being exponentially rarer (hence with lower values for $P(\phi)$) than closed class words like “more”. Experimental sampling by elicitation of child utterances during such exponential extinction may well give the appearance of all-or-none setting of parameters like NEG-placement and *pro*-drop claimed by Thornton & Tesan (2006).³

This lexicon includes non-standard holophrastic lexical items such as “more doggies”. Such spurious lexical entries can later be pruned if necessary on grounds of low relative frequency in the corpus as a whole, along with the spurious entries. Nevertheless, holophrastic lexical items such as “All gone,” may be sufficiently common as to be useful in their own right, and persist in the developing lexicon in

³This effect is related to the “winner-take-all” effect observed in Steels’ 2004 game-based account of the otherwise rather different process of establishing a shared vocabulary among agents who have no preexisting language.

parallel with their components.

It is of course possible that the adult will on occasion mistake the proposition that the child has in mind, or that the child will choose such a proposition wrongly, leading to false lexical associations. However, provided the two get it right most of the time, the same process of Bayesian re-estimation of conditional probabilities of these lexical hypotheses for each word will allow the latter to arrive at a correct lexicon.

4.2 Transitives

Up till now, we have been able to ignore the influence of the child's estimate of the prior conditional probability $P(\sigma|\tau)$ of a syntactic category given a semantic type in calculating $P(\sigma_i, \mu|\phi)$ in computing (5), the probability of a syntactic and semantic category given a word, because the examples have only admitted one syntactic category per semantic type per word.

However, unlike intransitive predicates and the determiner category considered in section 4.1, transitive verbs as presented in examples like the following could in principle be assigned either of the two syntactic categories in (15), both of which support a derivation of the logical form:⁴

(14) I see you! := $S : see'you't'$

(15) a. $see := (S \setminus NP) / NP : \lambda x \lambda y. see'xy$
 b. $see := *(S / NP) \setminus NP : \lambda y \lambda x. see'xy$

No SVO language/construction has ever been seriously argued to have a surface syntax corresponding to the second category. We can therefore safely assume either that it is not included in the universal set of possible syntactic categories for interpretations of type $(e, (e, t))$ at all, or that it has an extremely low prior probability.

Specifically, we will assume that the universally permitted set of transitive categories is the following, corresponding to the six basic constituent orders, here listed in order of decreasing frequency of attestation of the order in question.⁵

⁴We continue to assume for the sake of simple exposition that there is only one logical form supported by the context. In particular, we assume that the corresponding passive is not salient, or that if it is it has a distinct logical form from the active. We will abandon these restrictions later.

⁵We assume, following Baldrige (2002), that free word-

(16) a. $SOV := (S \setminus NP) \setminus NP : \lambda x \lambda y. see'xy$
 b. $SVO := (S \setminus NP) / NP : \lambda x \lambda y. see'xy$
 c. $VSO := (S / NP) / NP : \lambda y \lambda x. see'xy$
 d. $VOS := (S / NP) \setminus NP : \lambda x \lambda y. see'xy$
 e. $OVS := (S / NP) \setminus NP : \lambda x \lambda y. see'xy$
 f. $OSV := (S \setminus NP) \setminus NP : \lambda y \lambda x. see'xy$

The decreasing frequency of these orders appears to reflect two independent defeasible constraints. One favors linearization of subject before object. The other favors keeping the syntactic command relations between subject and object as reflected in order of combination the same as those in the logical form.⁶

Since (15b) violates the second of these constraints, we are justified in assuming it has a lower prior. Thus the child faced with the pair (14) effectively has only one candidate category for the transitive verb. However, this does not exhaust the problem of learning transitive verbs, because a context may support more than one category.

4.3 Contextual Ambiguity

Many languages, perhaps all, allow a number of lexical alternations of transitives, as in the case of English “chase/flee” where the same physical situation seems to support more than one logical form. How do children faced with examples like the following avoid the error of making an OVS lexical entry for “flee” with the meaning *chase*'?

(17) Pussies flee doggies!

It is important that examples of the verb class of which “flee” is the most common representative are rare. In particular, in comparison to 162 occurrences of inflected forms of the verb “chase,” there is exactly one occurrence of any form of “flee” in the entire CHILDES corpus. We are therefore justified in assuming that the child will have encountered plenty of unambiguous transitive verbs in utterances like (14) before encountering examples like (17).

This means that the probability of the category type $(S \setminus NP) / NP : \mu_{((e, (e, t)))}$ will be substantial at the time they eventually do encounter (17)—

order languages simply have more than one of these categories.

⁶Two of these categories, VSO and OSV, “wrap” their most oblique argument O(object) around their least oblique argument S(subject). (These categories are forced under the account of argument cluster coordination and the restriction to the combinator **BTS** in CCG—Steedman 2000b).

for the sake of illustration let's conservatively assume they have seen 1000 tokens—and adds one count each for these two categories. In that case, by (5), since $P(\mu_\tau|\phi)$ is the same for both, and $P((S\backslash NP)/NP|“flee”)$ is $\frac{25 \cdot 1000}{1001} = .25$, while $P((S/NP)\backslash NP|“flee”)$ is $\frac{25 \cdot 1}{1001} = .00025$, the lexical probability for the two entries stand in a ratio of 1000:1.

Thus, *provided the adult's intended meaning is available*, even if with low prior probability, then the child is in a position to assign the correct hypothesis a high probability. (Even if it is not available, the child will assign a low probability to the spurious lexical entry for *chase'*.)

Gleitman 1990 has described the process by which the child resolves contextual ambiguity as “syntactic bootstrapping,” meaning that it is the child's knowledge of the language-specific grammar, as opposed to the semantics, that guides lexical acquisition. However, in present terms such an influence on learning is simply emergent from the statistical model used in semantic bootstrapping. We will return to this point in the Discussion.

Like the related proposals of Siskind; Villavicencio; Zettlemoyer & Collins and the somewhat different probabilistic approach of Yang 2002, this proposal considerably simplifies the logical problem of language acquisition. In particular, it allows us to eliminate the Subset Principle of Berwick (1985), and attendant requirements for ordered presentation of unambiguous parametric triggers, both of which appear to present serious problems for the language learner (Angluin 1980; Becker 2005; Fodor & Sakas 2005). Nor does this move contradict widely-held assumptions concerning the “poverty of the stimulus”, and in particular the unavailability to the child of negative evidence. The child's progression from the universal superset grammar to the language-specific target grammar is entirely determined by positive evidence raising the probability of correct hypotheses at the expense of incorrect ones. The incorrect hypotheses that are eliminated in this way include any that are introduced by error and noise. The only evidence that the child needs in order to learn their language is a reasonable proportion of utterances involving sentences which are sufficiently short for them to deal with.

4.4 A More Realistic Lexicon

If children's exposure to language were merely confined to recitations of propositions they already had in mind, it would be a dull affair. It is not even clear why they would bother to learn language at all, as Clark (2004) points out in defence of a PAC learning model.

However, the worked example above is deliberately simplified in respect of the child's syntax and semantics. We know from Fernald et al. (1989) and Fernald (1993) that infants are sensitive to interpersonal meanings of intonation from a very early age. In English, intonation contour is used to convey a complex system of information-structural elements, including topic/comment markers and given/newness markers (Bolinger 1965; Halliday 1967; Ladd 1996), and is exuberantly used in speech by and to infants. It is this part of the meaning that constitutes the whole point of the exercise for the child, providing the motivation that Clark questions.

For example, it is likely that the child's representation of the utterance “MORE DOGGIES!” is more like (18), which uses the notation of Steedman 2000a, 2006b, in which [S] represents speaker modality (contributed by the LL% boundary tone), ρ indicates a rheme or comment (contributed by the H* pitch-accents), * marks emphasis or contrast (also contributed by the pitch-accents), and the category NP is “type-raised”, indicated by the annotation NP^\dagger :⁷

$$(18) \quad \begin{array}{c} \text{MORE DOGGIES} \\ \text{H*} \quad \text{H*} \quad \text{!} \\ \text{LL\%} \\ \hline \text{NP}^\dagger_{+, \rho} \quad \text{X}_\phi \backslash_* \text{X}_{\pi, \eta} \\ : \lambda p.p(*\text{more}'*\text{dogs}') : \lambda g.\pi[S]\eta g \\ \hline \text{NP}^\dagger_\phi : [S]\rho\lambda p.p(*\text{more}'*\text{dogs}') \\ \text{“Mummy makes the property afforded by more dogs} \\ \text{common ground.”} \end{array}$$

The set of type-raised NP categories licenced by UG that is schematized in (18) as NP^\dagger denotes the set of all order-preserving functions over functions-over-NP onto the results of applying those functions to the original NP. It includes categories of the following two forms, where T is a variable over all cat-

⁷The term *kontrast*, due to Vallduví & Engdahl (1996) means much the same as Halliday's “new”, and is so spelled to distinguish it from other notions of contrast, in particular any distinct notion of “topic contrast”.

6 Conclusion

This paper has argued that syntax is learned on the basis of preexisting semantic interpretations afforded by the situation of adult utterance, using a statistical model over a universal set of grammatical possibilities. The existence of the model itself helps the child to rapidly acquire a correct grammar even in the face of competing ambiguous semantics.

The fact that the onset of syntactically productive language at the end of the Piagetian sensory-motor developmental phase is accompanied by an explosion of advances in qualitatively different “operational” cognitive abilities suggests that the availability of language has a feedback effect, facilitating access to concepts that the child would not otherwise have access. Early work by Oléron (1953) and Furth (1961) on specific cognitive deficits concerning non-perceptually evident concepts arising in deaf children who had been linguistically deprived by being denied access to sign supports this view.

This means that Gleitman’s (1990) influential suggestion that it is the availability of syntax that enables the child to “syntactically bootstrap” lexical entries for verbs (such as “think”) that are not situationally evident is essentially correct. However, we have seen from the case of learning the verb “flee” in the face of competition from the meaning *chase* that it is the availability to the child of *a model of the relation between language-specific syntax and universal semantics* that makes this possible. It follows that the effects observed by Oléron and Furth, and Gleitman herself must have the character of *directing the child’s attention* to alternatives that are available to them, but which they would otherwise overlook, by sheer force of Bayesian priors on the conditional probability $P(\sigma|\tau)$ of a syntactic category given a semantic type. In that sense, we should probably refer to this effect as “grammatical” bootstrapping, since it is an effect that is both syntactic and semantic.

The theory presented here resembles the proposal of Fodor 1998 as developed in Sakas & Fodor (2001) and Niyogi (2006) in that it treats the acquisition of grammar as in some sense parsing with a universal “supergrammar”. As in that proposal, both parameters and triggers are simply properties of the language-specific grammar itself—in their case,

rules over independently learned parts of speech, in present terms, lexical categories.

It differs in assuming that the unordered logical form for the utterance is mostly available, with tolerable degrees of error and ambiguity. This means that the problem of syntactically ambiguous sentences to which STL is heir does not arise.

It also differs in the algorithm by which it converges on the target grammar. Rather than learning rules in an all or none fashion on the basis of unambiguous sentences that admit of only one analysis, it adjusts probabilities in a model of all elements of the grammar for which there is positive evidence for *all* processable utterances. In this respect, it more closely resembles the proposal of Yang (2002). However it differs from both in eschewing the view that grammar learning is parameter setting.

In equating language-specific grammar with a statistical model for parsing with universal grammar, the proposal bears an intriguing relation to the Maximum Spanning Tree (MST) parser (McDonald et al. 2005; McDonald & Pereira 2006b,a). This parser searches for the maximum-valued spanning tree-forming subgraph of a totally connected graph over the words of the string, using a perceptron-like maximum-margin discriminative model trained using pairs of strings and dependency trees. It has been applied to parsing “non-projective” or long-range dependencies, including crossing dependencies. It works best when the features over which the model is trained are grammar-like features such as position with respect to the verb, or morphological features. In particular, Çakıcı (2007) has shown that using CCG categories as features in a dependency-model of Turkish improves performance over the baseline in McDonald & Pereira (2006b). MST could therefore be seen as offering an alternative, discriminative, version of the present approach, according to which it could be used to learn weights for a language-specific set of features or categories drawn from a larger universal set.

If the parameters are implicit in the rules or categories themselves, and you can learn the rules or categories directly, why should the child or the theory bother with parameters at all? For the child, all-or-none parameter-setting is counterproductive, as it will make it hard to learn the many languages which have inconsistent settings of parameters across lexi-

cal types and exceptional lexical items, as in German and Dutch head finality, and English expressions like the following:

(24) Doggies galore!

Therefore, the fact that languages show violable tendencies to consistency for values of parameters like headedness across categories for related semantic types such as verbs and prepositions probably stems from considerations of overall encoding efficiency for the grammar as a whole, of the kind captured in notions like Minimal Description Length (MDL). Such considerations may be relevant to comparing entire grammars for the purpose of explaining language change, as in the work of Briscoe (2000). Their presence will under the present theory make the task of learning easier, by raising prior probabilities in the model for rules and categories that actually do recur. But it is less clear that representing them explicitly, rather than leaving them implicit in the model, will help the individual child learning a specific grammar, word-by-word.

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